

Temperature dependence of protein-hydration hydrodynamics by molecular dynamics simulations

Edmond Y. Lau^a, V.V. Krishnan^{b,c,*}

^a *Biology and Biotechnology Division, Lawrence Livermore National Laboratory, Livermore, CA, United States*

^b *Department of Applied Science and Center for Comparative Medicine, University of California Davis, Davis, CA, United States*

^c *Department of Chemistry, California State University Fresno, Fresno, CA, United States*

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Abstract

The dynamics of water molecules near the protein surface are different from those of bulk water and influence the structure and dynamics of the protein itself. To elucidate the temperature dependence hydration dynamics of water molecules, we present results from the molecular dynamic simulation of the water molecules surrounding two proteins (Carboxypeptidase inhibitor and Ovomuroid) at seven different temperatures ($T=273$ to 303 K, in increments of 5 K). Translational diffusion coefficients of the surface water and bulk water molecules were estimated from 2 ns molecular dynamics simulation trajectories. Temperature dependence of the estimated bulk water diffusion closely reflects the experimental values, while hydration water diffusion is retarded significantly due to the protein. Protein surface induced scaling of translational dynamics of the hydration waters is uniform over the temperature range studied, suggesting the importance protein–water interactions.

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1. Introduction

Water plays a crucial role in determining the structure, dynamics, and function of proteins and other biological macromolecules. It is implicated in the folding, unfolding, and stabilization of protein three-dimensional structure, as well as in the internal dynamics and function [1–9]. Protein–water interaction affects the water molecules near the protein, leading to a behavior that is very different from bulk water [10–12]. These water molecules, widely known as interfacial or surface water molecules can be considered in general terms as hydration water, and a better understanding of their properties is necessary to gain insight into various biological mechanisms of protein function [13–15]. The dynamics and other properties of water near a protein surface has been elucidated by a multitude of experimental methods: these include calorimetry, thermody-

namic measurements [16], nuclear magnetic resonance (NMR) analysis [17–19], X-ray and neutron small-angle scattering, [20], high resolution X-ray crystallography [21–25], and high resolution neutron crystallography [26,27]. All these studies showed that water molecules on the protein surface mainly occupy well-defined hydration sites (time and space averaged water molecule position), providing stability to the protein structure and mediating interactions with other components of the cell.

There is increasing evidence over the past decade and in particular in the last four years that hydration water molecules play a synergetic role in protein structure, dynamics, as well as function [6–9]. Although experimental measurements indirectly show that, the physical properties of hydration water molecules are different from that of bulk water, molecular dynamics (MD) simulations are capable of providing information on the time and the geometric scale commensurate with the diffusive motions of individual water molecules responsible. Several MD studies have been performed on protein solution or protein crystals and provide a wide range of observations and at times contradictory [28–30]. Lack of consistent experimental and

* Corresponding author. Department of Chemistry, California State University Fresno, Fresno, California, United States. Tel.: +1 559 278 7944.

E-mail addresses: vvkrishnan@ucdavis.edu, krishn@csufresno.edu (V.V. Krishnan).

computational investigations on model protein–water systems make it difficult to compare the structural and dynamical results across the different studies. In addition, most of the calculations have been restricted to either short simulation length or to a single temperature. As a first step towards generating a consistent set of data, we present a molecular dynamic study of water molecules in two protein systems, as a function of temperature.

Molecular dynamics simulation of protein–water systems of two different model proteins, Carboxypeptidase inhibitor (CPI) and Ovomuroid (OVO), in explicit water as a function of temperature from 273 K to 303 K is presented. The choice of the proteins was decided by their size that allows sampling of the water dynamics that are computationally inexpensive and at the same time provide the necessary features to generalize the results. CPI is a small protein of 39 residues (MW=4.36 kD) with the three-dimensional structure well stabilized by intramolecular disulphide bonds [31]. OVO is a medium sized protein of 56 residues long (MW=6.04 kD). Analysis of the molecular dynamics simulation trajectories of the water molecules provides characteristic differences in the dynamic behavior between the bulk and surface water molecules. In particular, we find that our results are similar to the trend suggested by the modified Stokes–Einstein equation for biomolecular hydration [32]. These results perhaps provide a first set of consistent

simulation data to understand the temperature dependence of the translational dynamics of water molecules.

2. Results

2.1. Temperature dependence of radial distribution functions

The structural organization of water at the protein interface is generally described by protein–water radial distribution functions that represent the relative probability of finding any solvent molecule at a distance ‘ r ’ from a specific solute atom [33,34]. The radial distribution function (RDF) of the water molecules around the proteins has been calculated for both polar and nonpolar residues separately. Fig. 1 shows the plots of the radial distribution function of the backbone oxygen, carbonyl and nitrogen to the water oxygen at three representative temperatures (at 273, 288 and 303 K, continuous-black, long-dashed-red, and dashed-green) for the protein CPI with the left panels (a, c and e) for the nonpolar residues and the right panels (b, d and f) for the polar residues. Similarly, Fig. 2 shows the results for the protein Ovomuroid. The plot of the radial distribution function is used to evaluate the quality of the dynamic trajectories. All the distribution functions in Figs. 1 and 2 show the characteristic peaks, with the first one centered around 2–3 Å, arising from the

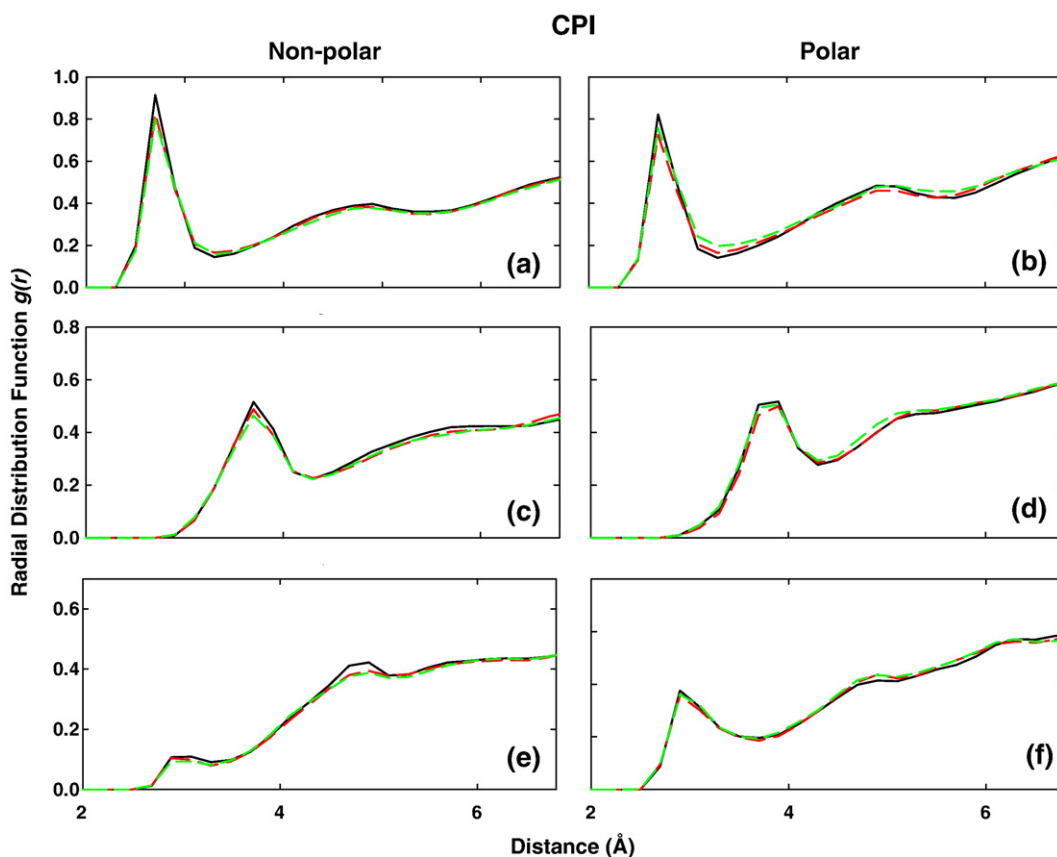


Fig. 1. Uncorrected water–protein radial distribution functions around equilibrated CPI, nonpolar (left panels) and polar (right panels) as a function of the distance between backbone oxygen (a and b), carbonyl (c and d) and nitrogen (e and f) atoms to the water oxygen atom. Three representative temperatures at 273, 288 and 303 K were shown as continuous (black), long-dashed (red) and dashed (green) lines. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

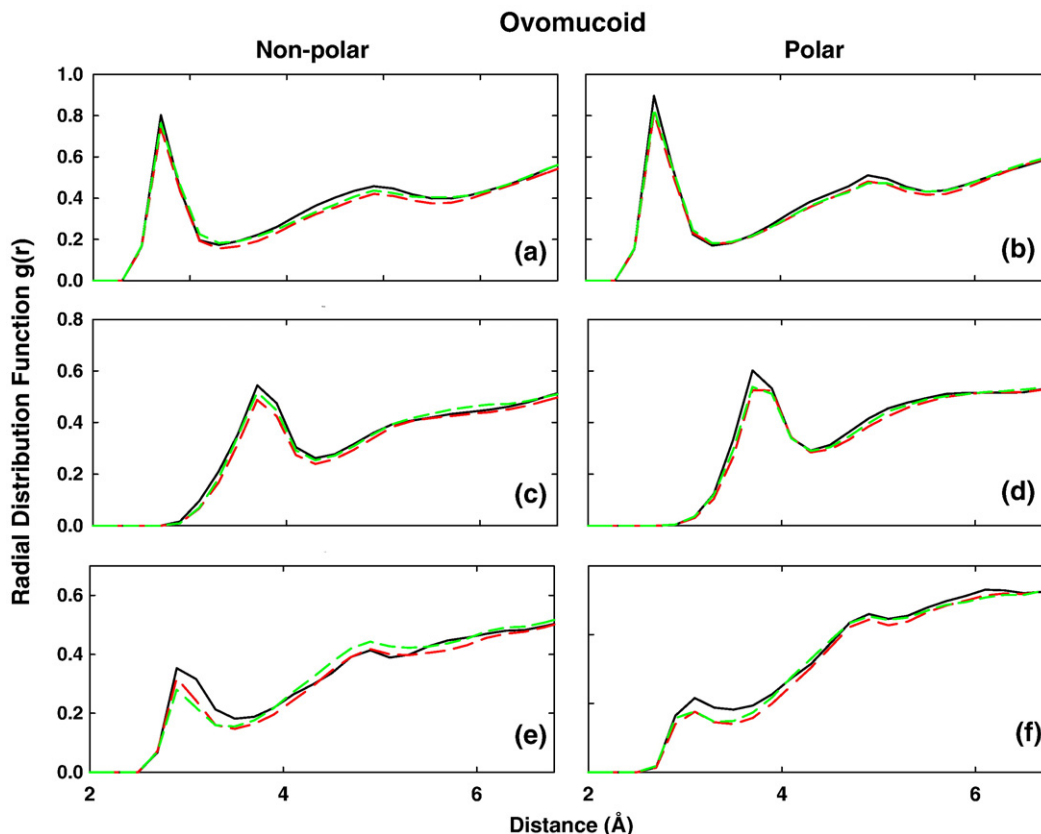


Fig. 2. Uncorrected water–protein radial distribution functions around equilibrated Ovomuroid, nonpolar (left panels) and polar (right panels) as a function of the distance between backbone oxygen (a and b), carbonyl (c and d) and nitrogen (e and f) atoms to the water oxygen atom. Three representative temperatures at 273, 288 and 303 K were shown as continuous (black), long-dashed (red) and dashed (green) lines. (For interpretation of the references to colour in this figure legend, the reader is referred to the web version of this article.)

strong interaction of the water oxygen with hydrogen bond acceptor groups of the protein surface, and the second peak at a location farther from the first one (4–5 Å) due to interaction between the water oxygen and nonpolar heavy atoms of the proteins [33,35]. Figs. 1 and 2 also show the bulk limit of the radial distribution is generally reached for distances greater than 8 Å from the protein surface, supporting the lack of persistence of the structural organization of bulk water. For both proteins, the first peak for solvent exposed residues' the O, C and N distribution occurs at 2.8, 3.8 and 3.0 Å, respectively and the distribution functions at 273 K have slightly higher values than the values at the higher temperatures.

2.2. Translational dynamics of bulk and protein-hydration waters

The combination of Einstein's fluctuation dissipation theorem [36] and the macroscopic continuum hydrodynamics [37] for the friction coefficients of a sphere of radius 'a' undergoing steady state translational diffusion yields the Stokes–Einstein equation,

$$D_s = \frac{k_B T}{6\pi\eta a} \quad (1)$$

where k_B is Boltzmann's constant ($1.3806 \times 10^{-23} \text{ m}^2 \text{ kg s}^{-2} \text{ K}^{-1}$), T is the temperature in K, and η is water viscosity (Ns m^{-2}). The viscosity of water, as a function of temperature, follows the definition of a glass-forming liquid [38] and at temperatures above 242 K, it follows an empirical Vogel–Tamman–Fulcher (VTF)-type relationship ($\eta = A \exp(-B/(T - T_0))$), where A , B , and T_0 are constants [38]. Diffusion constants of water have been measured using nuclear magnetic resonance (NMR) pulsed-field-gradient (PFG) methods [39] and these measurements also followed VTF-type relationship ($D_s = A \exp(-B/(T - T_0))$), with constants $A = 4.00 \times 10^{-8} \text{ m}^2 \text{ s}^{-1}$, $B = 371 \text{ K}^{-1}$ and $T_0 = 169.7 \text{ K}$. These numbers are close to the one derived by Miller [38]. Therefore, a plot of D_s versus T/η is expected to be linear and can be used as a quantitative measure of the change in the diffusion constant as a function of temperature. Fig. 3 shows plots of the diffusion coefficient as a function of T/η for CPI (Fig. 3a) and Ovomuroid (Fig. 3b). Experimentally measured bulk water diffusion coefficients [39] are shown as open circles in both Fig. 3a and b. Diffusion constant of the bulk water from the molecular dynamics simulations are shown as filled circles. Hydration (surface) water molecules calculated using a cutoff at 3.4 Å and 5.0 Å are shown by triangles and squares, respectively. The bulk water diffusion constants (filled circles in Fig. 3) are calculated independently for CPI and Ovomuroid systems. The straight lines thorough the points

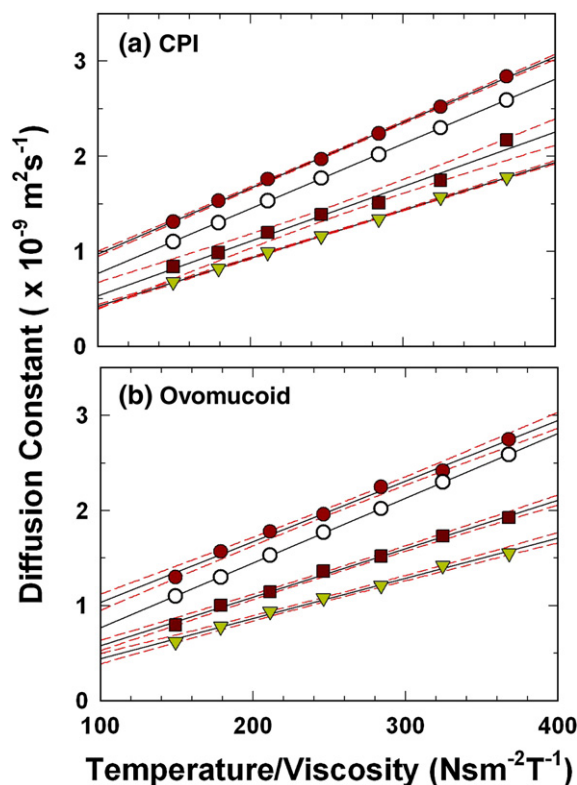


Fig. 3. Plot of D_s versus T/η for the various water molecules for (a) CPI and (b) Ovomucoid. Experimentally determined bulk water (open circles), bulk water molecules in the simulation (filled circles) and hydration (surface) water molecules on the protein (triangles and filled squares) are shown. The hydration water diffusion with a cutoff of 3.4 Å and 5.0 Å were shown as triangles and squares, respectively for each protein. The experimental bulk water diffusion values are same in both (a) and (b), while the simulated values are calculated separately for CPI and Ovomucoid. The straight lines are the linear fit and the dotted lines correspond to the respective 95% confidence limits and the confidence limits for the experimental values are not plotted.

represent corresponding linear fit and the dashed lines correspond to the respective 95% confidence limits. The literature values for η follow the well-defined empirical relations for pure water [39] and it is assumed that the bulk viscosity is not altered at low protein concentration.

Table 1 summarizes translational diffusion constants for bulk and hydration water from the CPI and Ovomucoid simulations and the respective experimental bulk water values. Table 1 also lists the reduction in the translational diffusion constant of the hydration water in percentage for each temperature with respect to the corresponding bulk water diffusion coefficients. It is evident from Fig. 3 and from Table 1 that the diffusion coefficients of bulk water in the protein water system is very similar to the respective experimental values and the diffusion behavior of the hydration water is retarded significantly, with a temperature dependent scaling. At low temperatures, the scaling effects are larger than at higher temperatures for both the proteins; For example, using a cutoff value of 3.4 Å, the hydration water diffusion is scaled by 48–54% with respect to the bulk water at lower temperatures (273 K), and between 37 and 43% at higher temperatures (303 K). At a cutoff value of 5.0 Å, the scaling is 35–38% in the low temperature region (273 K) and 23–30% at the high temperature region (303 K). Within the cutoff radius of 5 Å includes waters in contact with nonpolar heavy atoms, such as methyl groups. These interactions are weaker than the polar interactions observed within the 3.4 Å cutoffs and allow the water to diffuse away from the protein more easily. As the water molecules are sampled at a higher cutoff value, farther away from the protein surface the results consistently show that the hydration water molecules progressively tend to attain the characteristics of the bulk water behavior. Although the actual scaling at each temperature for CPI and Ovomucoid is different, the rate of scaling obtained using the linear fit with respect to (T/η) is similar, for both the scaling factors. The variation of D_s values with respect to (T/η) is analyzed using linear regression methods and the results are summarized in Table 2. The temperature dependence of bulk water from the protein water system is very close to that of the experimental values ($6.91 \pm 0.06 \text{ N/K}$ and $6.37 \pm 0.02 \text{ N/K}$, for CPI and Ovomucoid, respectively), and the experimental bulk water has a slope of $6.64 \pm 0.01 \text{ N/K}$. The rate of change of D_s with T/η shows how closely the simulated values resemble the experimental values. The same metric can also be used as a measure to compare the diffusion characteristics between the surface and bulk waters in the protein–water system. Overall,

Table 1
Translational diffusion constants of the bulk and hydration waters

Translational diffusion constant ($\times 10^{-9} \text{ m}^2 \text{ s}^{-1}$)											
Experimental ^a		CPI					Ovomucoid				
Temperature	Bulk water	Bulk water	Hydration water		ΔD_S (%)		Bulk water	Hydration water		ΔD_S (%)	
			(D_S^H)					(D_S^H)			
(K)		(D_S^0)	3.4 Å	5.0 Å	3.4 Å	5.0 Å	(D_S^0)	3.4 Å	5.0 Å	3.4 Å	5.0 Å
273	1.10	1.31	0.68	0.84	48.1	35.9	1.30	0.62	0.80	52.3	38.7
278	1.30	1.53	0.82	0.99	46.4	35.6	1.57	0.78	1.01	50.3	36.0
283	1.53	1.76	0.99	1.20	43.8	31.8	1.78	0.94	1.15	47.2	35.6
288	1.77	1.97	1.16	1.39	41.1	29.6	1.96	1.08	1.36	44.9	30.5
293	2.02	2.24	1.34	1.51	40.2	32.5	2.25	1.21	1.52	46.2	32.5
298	2.30	2.52	1.57	1.75	37.7	30.7	2.42	1.42	1.73	41.3	28.4
303	2.59	2.84	1.78	2.17	37.3	23.5	2.75	1.55	1.93	43.6	30.0

^a Experimental values were obtained from [75].

Table 2
Linear regression analysis of the temperature dependence of hydration waters

System	Bulk water			Hydration water		
	Intercept	Slope	CC	Intercept	Slope	CC
Experimental	0.14±0.01	6.64±0.01	>0.99			
CPI–water	0.28±0.01				5.05±0.04	
(3.4 Å)		6.91±0.06	>0.99	−0.08±0.01		>0.99
(5.0 Å)				−0.04±0.01	5.74±0.04	>0.99
Ovomucoid–water	0.39±0.05				4.24±0.1	
(3.4 Å)		6.37±0.02	>0.99	0.03±0.01		>0.99
(5.0 Å)				−0.07±0.03	5.1±0.01	>0.99

CC: correlation coefficient.

the temperature dependence of the translation diffusion of bulk water from the simulations is in reasonable agreement of the simulations to experiments. Comparison of the calculated diffusion coefficients between the bulk and hydration water molecules (Fig. 3 and Table 2) shows the protein induced rate change of solvent translational diffusion coefficient with respect to T/η is $\sim 30\%$ at a cutoff 3.4 Å (26.9% and 33.3% for CPI and Ovomucoid, respectively) $\sim 18\%$ at a cutoff 5.0 Å (16.9% and 19.9 for CPI and Ovomucoid, respectively) over the temperature range studied.

2.3. Influence of polar and nonpolar residues on water diffusion

Interaction between the protein and water molecules is not uniform at the surface and it is largely determined by the nature of the surface exposed amino acids. Table 3 lists the diffusion coefficient of water molecules (calculated at a cutoff of 3.4 Å) close to the surface polar and nonpolar residues. In general the diffusion constant of water molecules close to the polar residues are slightly higher than the nonpolar ones. The difference in the diffusion constants are in the range of 0.1 to 0.3 ($10^{-9} \text{ m}^2 \text{ s}^{-1}$) and these differences are tend to be slightly larger for CPI than for Ovomucoid. The temperature dependence on the influences of diffusion coefficients between polar and nonpolar residues is complex and can arise from several factors: For example the hydrophobic effect increases with increase in temperature [40,41] reflecting increased disparity between perturbed waters forced to align themselves around nonpolar groups [42] and those free to interact with bulk solvent.

2.4. Hydration hydrodynamics

The observed variation in the diffusion coefficient of protein-hydration water molecules, from the Stokes–Einstein equation (Eq. (1)) can arise either due to a change in the viscosity (η) or the radius (a) or both. Experimental measurement of the bulk water rotational correlation time (τ_s) follows the viscosity over a wide range of temperatures [43] and in fact the observed change in the radius is only 1.7% in the temperature range of -10° to 60°C [44]. Therefore, the assumption that modulation of the translational dynamics of hydration water molecules is

predominantly due local changes in the viscosity induced by frictional coupling between the protein and surface waters is reasonable.

Hydration hydrodynamics model shows that the frictional coupling between protein and solvent is a major contributing factor for observed changes in protein dynamics [32]. In this model, the ratio of the translational diffusion constant of a protein that is perturbed by the solvent (D_P) to the unperturbed (D_P^0) is given by

$$\frac{D_P}{D_P^0} = 1 - (1 - \alpha_T) \left(1 - \frac{\eta_o}{\eta_s} \right) \quad (2)$$

where η_o and η_s are the viscosity of bulk and surface water molecules, respectively and α_T is the geometrical quantity for the translational motion given by

$$\alpha_T = \left(\frac{V_P}{V_P + V_S} \right)^{\frac{1}{3}} \quad (3)$$

where V_P is the volume of the protein immersed inside an incompressible liquid of viscosity η_s within a spherical shell of volume V_S and the bulk value of viscosity η_o everywhere else. When $V_S=0$ and/or $\eta_s=\eta_o$, water molecules are not influenced by the protein and conversely the protein dynamics is described by the Stokes–Einstein equation (similar to Eq. (1), but for the proteins). At the other limit when $\eta_s \gg \eta_o$, referred to as ‘solvent-berg’ limit, the protein molecule has the most influence

Table 3
Diffusion coefficients of water molecules at the polar and nonpolar surface residues

Temperate (K)	^a Translational diffusion constant ($\times 10^{-9} \text{ m}^2 \text{ s}^{-1}$)			
	Ovomucoid		CPI	
	Polar residues	Nonpolar residues	Polar residues	Nonpolar residues
273	0.61	0.47	0.68	0.51
278	0.80	0.66	0.86	0.65
283	0.96	0.83	1.02	0.81
288	1.05	1.00	1.21	0.97
293	1.20	1.08	1.36	1.14
293	1.39	1.33	1.66	1.23
303	1.52	1.43	1.88	1.44

^a Diffusion coefficients are calculated at a cutoff value of 3.4 Å.

Table 4
Estimation of diffusion scaling of water due to hydration

Protein	MW (kD)	Surface area (\AA^2)	Molecular volume (\AA^3)	Stokes volume (\AA^3)	α_T	D_P^0	Hydrodynamic scale (\AA)	D_P^H	ΔD_S (%)
CPI	4.28	2776.40	4364.20	7494.53	0.71	16.4	2.0–4.0	14.49–12.74	39–75
OVO	6.02	3973.20	6486.00	11056.37	0.72	14.4	2.0–4.0	12.75–11.06	41–82

D_P and D_P^0 are solvent and unperturbed translational diffusion constants, respectively and α_T is defined in Eq. (3).

on hydration water molecules and a clear distinction with bulk water is established [32].

Rewriting Eq. (2) in terms of the solvent translation dynamics with the assumption that the radius of the water molecule remains the same between bulk and hydration conditions,

$$\frac{D_S^H}{D_S^0} = 1 - \left(\frac{1}{1 - \alpha_T} \right) \left(1 - \frac{D_P}{D_P^0} \right) \quad (4)$$

Eq. (4) shows that the translational dynamics of hydration water is directly related to the dynamic parameters of the protein. Therefore, it is possible to estimate the RHS of Eq. (4) to determine the expected scaling of the hydration waters with respect to bulk water. The two parameters that need to be estimated are α_T and D_P/D_P^0 .

Geometrical factor α_T is normally estimated from the three-dimensional structural parameters by assuming that the volume

of the hydration shell (V_S) is proportional to the protein surface area A_P ,

$$V_S = \lambda_S A_P \quad (5)$$

where the effective shell thickness λ_S , can be assumed to be 2 \AA (less than its diameter, 2.8 \AA) [32]. Table 4 lists the molecular properties for CPI and Ovomuroid, including surface area, molecular volume, and Stokes volume along with the estimated α_T values. Using the molecular surface area of CPI and Ovomuroid estimated from their 3D structures (Table 4), the average value for α_T becomes 0.76. As a comparison, the geometrical factor estimated for rotational contribution is 0.56 and the corresponding translational value is 0.82 ($\alpha_T = \sqrt[3]{\alpha_R}$) for lysozyme. Alternatively, we have calculated the geometrical factor, where V_S in Eq. (5) is assumed to be equal to the corresponding Stokes volume (Table 4) of the protein. This procedure resulted in

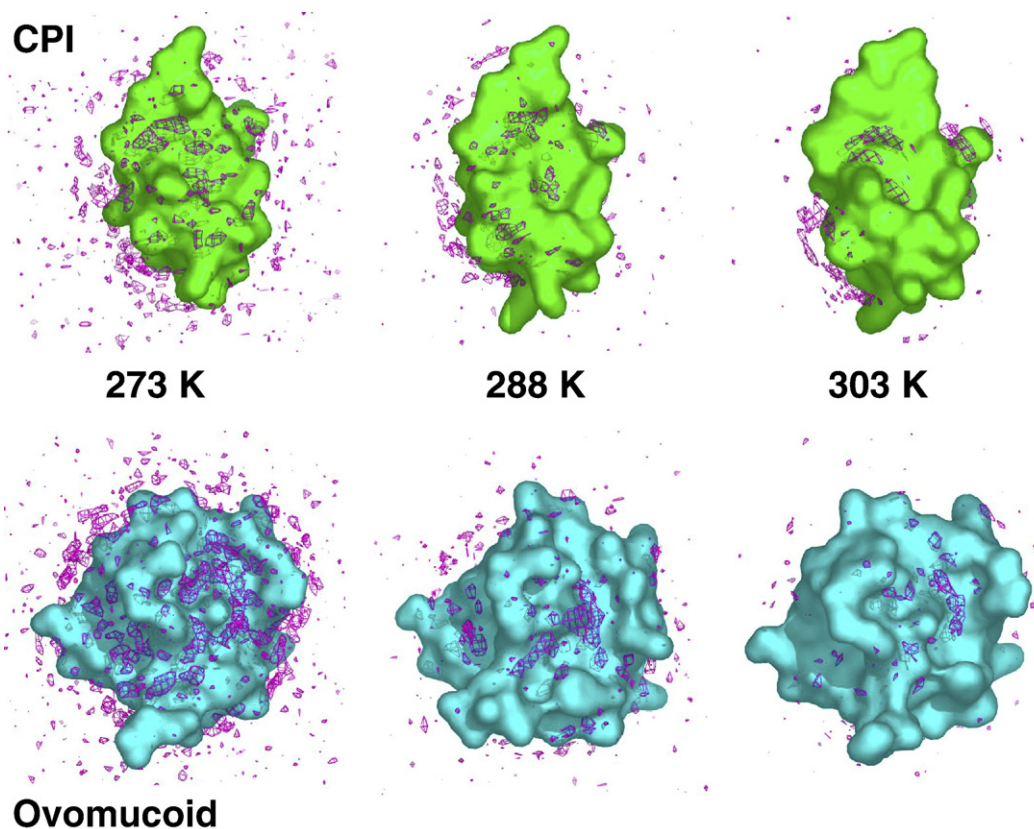


Fig. 4. Schematic representation of hydration hydrodynamics effects for CPI and Ovomuroid at the top and bottom respectively. The top row shows cartoon views of CPI at 273, 288 and 303 K, respectively where the grids represent density of water molecules surrounding the protein and bottom row show a similar representation for OVO. (Reader is referred to the color figure in the web version of the article.)

slightly smaller values of $\alpha_T \sim 0.71$ for both proteins than the first procedure.

In order to determine the second ratio (D_P/D_P^0) D_P^0 diffusion constant of the nonhydrated protein is traditionally estimated from Eq. (1), where the effective radius is determined from the volume estimated by $V_P = M_P \bar{v}_P$, where M_P is the molecular weight and \bar{v}_P is the partial specific volume ($0.073 \text{ m}^3 \text{ kg}^{-1}$). To account for the temperature dependence of D_P values, we calculated the translational diffusion constant of the proteins as a function of the hydration-scaling factor (variable effective atomic radius) and the results are extrapolated to no-hydration to determine D_P^0 (D_P solvent unperturbed diffusion). Fig. S1 (supporting information) shows the plot of the calculated self-diffusion coefficient for CPI and Ovomucoid as a function of the scaling factor (see Materials and methods) and averaged over the range of temperatures simulated (273–303 K) along with the linear regression (continuous lines) and confidence interval at 95% (dotted lines). The intercept that corresponds to D_P^0 is estimated to be $16.4 \times 10^{-10} \text{ m}^2 \text{ s}^{-1}$ ($\text{m}^2 \text{ s}^{-1}$) and $14.4 \times 10^{-10} \text{ m}^2 \text{ s}^{-1}$ ($\text{m}^2 \text{ s}^{-1}$), for CPI and Ovomucoid respectively. Estimation of D_P is approximate as the exact nature of the hydration depends critically on the surface composition. Comparison of the rotational correlation times of proteins determined using NMR based relaxation methods [45,46] suggest that scaling factors typically vary between 2.8 Å and 3.8 Å, with the distribution centered at 3.3 Å. Therefore when using a hydration-scaling radius of 3.3 Å to estimate D_P , the hydration hydrodynamics theory predicts a reduction in the translational diffusion coefficient of hydration water between 39 and 82% (39–75% for CPI and 41–84% for Ovomucoid), with respect to the bulk water over the temperature range simulated. In comparison, MD simulations (Table 1) estimate a reduction of 35–52% with respect to the bulk water (37–48% for CPI and 43–52% for Ovomucoid). Increasing the cutoff value to determine the hydration water diffusion constants from 3.4 to 5.0 Å (Table 1), this range reduces to 23–38%. This change in the reduction is an outcome of the fact that at 5.0 Å cutoff, the protein surface has less influence on the hydration waters and adopts more ‘bulk-like’ behavior. Although the hydration hydrodynamics based prediction do not match with the MD simulations perfectly, there is a good agreement between the results. For example, using the experimental information on ^{17}O magnetic resonance dispersion studies, Halle and Davidovic [32] adopted an average value of $\langle \tau_0/\tau_s \rangle$ (ratio of the rotational correlation times of bulk and hydration water) to be 0.35. Indeed, experimental rotational correlation based validation is a better method as it is much more sensitive and localized in comparison with the translational diffusion. It must be emphasized that variations in D_P values estimated from the hydrodynamics calculations are approximate as they do not account for the variation in the temperature and viscosity explicitly. More importantly, these results do not reflect the finer changes that occur locally on the protein surfaces such as cavities.

3. Discussion

Water mobility in the proximity of the protein surface exhibits a wide range of dynamical behaviors; from very tightly

bound water to highly mobile water molecules. Different categories of water behavior can be characterized depending on their residence times. One type is strongly bound to (in) the protein, which can be identified crystallographically and plays an important role in stabilizing the native structure. The residence time of these water molecules is usually in the range of 10^{-9} to 10^{-3} s. Another type of water is more dynamic (shorter residence times) and is interfacial in nature. The third type of water is in the vicinity of the protein surface but not directly interacting with the protein and displays bulk-like behavior. Our main interest is in the dynamics of the third class of water molecules that predominantly determine the hydration structure on protein surfaces.

The radial distribution functions of water with respect to various protein atomic sites reveal the structural organization of water near the protein surface [8,47]. The radial distribution functions around the polar and nonpolar atomic sites have similar distribution between the two proteins studied. The effect of polar versus nonpolar residue’s influence is more clearly seen in the respective water diffusion coefficients (Table 3). Temperature dependence of the hydration hydrodynamics is schematically shown in Fig. 4. Fig. 4 was generated by placing the protein at the origin at every time step. A 50 Å^3 grid with 1 Å^3 spacing was used to count up the number density of the oxygen’s in water for 1 ns. The top and bottom rows show the results for CPI and Ovomucoid, respectively. With increase in temperature density of water molecules surrounding the protein decreases. It is interesting to note that the change in the density is not uniform around the surface, with concave surfaces on both the proteins continue to maintain a higher density of water molecules even at higher temperatures. Surface shape effects are not unusual as evidenced by Hua et al. [47] that concave regions have a broader distribution compared to the sites in the convex region. Though the surface composition of the protein affects the hydration dynamics, the proteins themselves do not undergo any large-scale dynamics over the simulation length. For example, the variation in the radius of gyration (R_g) over the last 1 ns of the simulation of the protein shows only a little variation comparison with the R_g estimated from their respective X-ray structures (Table S1).

Extensive experimental information on the rotational and translational dynamics of bulk water is available. However, characterization of the hydration water is often inferred indirectly from the dynamic parameters of the protein. Experimental values of hydration water determined using magnetic resonance dispersion studies are about 5 times smaller than the bulk water [6] and that by neutron scattering tend to predict much less that factor of 5 [1]. Recently, Marchi et al. [48], have performed MD simulations of lysozyme at 300 K found that hydration water dynamics is scaled between 3 and 7 times depending on the definition of the hydration shell. Our results are in broad agreement with the magnetic relaxation dispersion studies and other MD simulations in general. We have shown here how the translational dynamics of water molecules can be followed using MD simulations and explained based on hydration hydrodynamics. The exact nature of the mechanism however needs extensive and accurate experimental

data on the global translational motion of proteins as a function of temperature.

At large distances from the protein surface, as is presented here, the bulk water diffusion results are closely reproduced by simulation. However, the simulation results on the surface water molecules tend to be more inconsistent [5]. In addition to the current results, several important observations were made and these can be classified into three major classes; (a) anisotropic diffusion of water on the protein surface [5,49], (b) anomalous diffusion of the water that introduces a nonlinear behavior to the Stokes–Einstein equation to describe the water diffusion in the presence of proteins [50–52] and (c) apparent increase in the density of water molecules close to the protein surface [20,53–55]. How each of these earlier observed protein surface induced effects on the translational behavior of the hydration water molecules needs much more elaborate study than what is presented here. Our goal was to first determine the temperature dependence of the hydration waters in proteins and then to determine how the simulations relate to hydration hydrodynamics theory. The agreement between the simulations and the theory is modest and most of the discrepancy between them can be traced to a large extent to the estimation of D_p .

4. Conclusions

Water plays a primary role in the flexibility of proteins and is critical to the conformational changes required for enzymatic activity [9]. The frictional coupling between protein motions and water dynamics has been suggested that fluctuations of the hydration water can slave the protein dynamics and thus affect its function [29,56,57]. The interplay between the protein and solvent complexity has several intriguing open questions, for example how much water (quantity) is affected by the presence of the protein. Most X-ray crystallographic studies have suggested that only the first solvent layer is affected, whereas calorimetric studies suggest that more than one layer is affected. Recently, Bano and Marek [58] have investigated the volume properties of protein-hydration layers by Monte Carlo modeling. The thickness of the thermal volume layer as calculated in their framework of the scaled particle theory is 0.6–0.65 Å. This value is significantly lower than ones presented for proteins in earlier papers (where proportionality between the hydration level and the area of charged and polar surfaces was assumed), but is close to the value published for small solute molecules. At the other extreme, certain glycoproteins tend to be much more hydrated than most globular proteins and a scaling factor of >5.5 Å is required to fit the temperature dependent translational diffusion coefficient. These differences in hydration properties could be natural to the protein and its function, in particular for proteins that function at extreme environments such as thermophilic or antifreeze proteins. We expect that new experimental approaches to measure the dynamic properties of the hydration layer and improved simulation methods will shed additional information. Our results provide one of the necessary steps that will lead to a comprehensive understanding of the role of hydration hydrodynamics in proteins structure, dynamics, as well as function.

5. Materials and methods

5.1. Molecular dynamics simulations

All molecular dynamics simulations were performed with Amber 7 [59] using the Cornell force field [60]. The proteins were chosen because of their small size and can be simulated with an overall neutral charge, thus no counterions are necessary. The Carboxypeptidase inhibitor (RCSB ID, 1H20, first 37 residues) [61] and Ovomuroid (RCSB ID, 2OVO) [62] were prepared in the following manner. The proteins were solvated in boxes of SPC/E [63] water sufficient to have 15 Å of water between the protein and the interface. SPC/E water was chosen because of its well-characterized behavior over a large range of temperatures [64]. The system was energy minimized using a combination of steepest descents and conjugate gradient methods. Constant pressure, constant temperature molecular dynamics [65] was performed on the energy-minimized system to randomize the water and to adjust the water density. A time step of 1 fs was used and the SHAKE algorithm was used to constrain bonds containing hydrogen [66]. The system was coupled to a heat bath at 303 K. Particle mesh Ewald summation was used to treat the long range interactions using a 9 Å cutoff in direct space with an 1 Å grid [67]. The NPT simulations for the Carboxypeptidase inhibitor and Ovomuroid were performed for 200 ps.

The final structure from the NPT simulation was energy minimized. This energy-minimized structure was used as the starting structure for all the NVE simulations and the box size was adjusted to have the appropriate density at the given temperature. All the NVE simulations started at 0 K and the velocities on the atoms were reassigned until they were at the appropriate temperature. All other aspects of the simulations were the same as stated above. Each simulation at a given temperature was run for a total of 2 ns with the last 1 ns were used for analysis.

The mean squared displacements (MSD) for bulk solvent were calculated in 100 ps windows and averaged. Diffusion constants for the bulk solvent were estimated from the slope of the MSD and multiplied by 5/3 to obtain the correct units (the mean squared displacement plotted against time for the simulation data gives a slope in Å²/ps. To convert to the appropriate units for a diffusion constant we get cm²/s (*10) and divide by 6 (for the degrees of freedom)). Hydration water was defined using two independent values, within 3.4 Å of a heavy protein atom and 5.0 Å of a heavy protein atom. Inspection of the MSD for the hydration waters over 100 ps shows two regimes. The MSD is linear to approximately 50 ps at the different temperatures but after 50 ps, the slope of the MSD increases (likely showing the hydration water exchanging to the bulk). The diffusion constants for the hydration waters were estimated with 50 ps windows and averaged.

5.2. Protein hydrodynamic calculations

Translational diffusion tensor values were calculated based on the beads model approximation of García de la Torre and Bloomfield [68]. This method has been used successfully to calculate translational as well as rotational diffusion tensors of

proteins [46,69–73]. In this method, the protein is modeled as a collection of point sources of friction (denoted as beads) with hydrodynamic tensor interactions between them. The rotational diffusion tensor is calculated from a set of linear equations solved by integrating a $3N \times 3N$ matrix, where N is the number of atoms determined from the structure of the protein. The program DIFFC, based on the beads theory [73], was used in the present work. All atoms were considered as beads of equal size for a range of different values ($\sigma = 1.5$ to 5.5 in steps of 1 \AA , and at 7 temperature values ranging from 273 K to 303 K) for purposes of calculating the diffusion tensor as a function of temperature. Experimental values of the viscosity (in N s m^{-2}) of pure water [74] were used. The overall isotropic translational self-diffusion coefficient was calculated by taking the average of the principal values of the diffusion tensor.

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Appendix A. Supplementary data

Supplementary data associated with this article can be found, in the online version, at [doi:10.1016/j.bpc.2007.07.004](https://doi.org/10.1016/j.bpc.2007.07.004).

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